

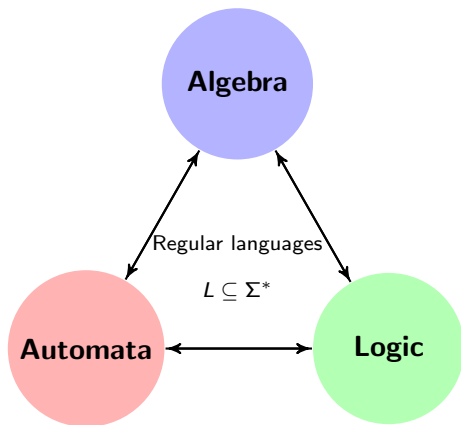
# Automata, Logic and Algebra for (Finite) Word Transductions

Emmanuel Filiot

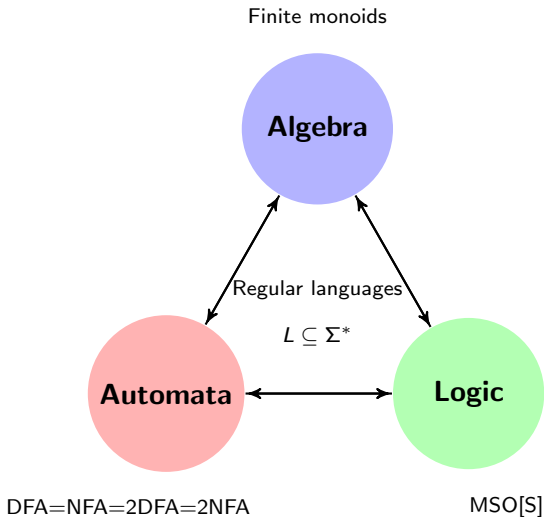
Université libre de Bruxelles & FNRS

Highlights of Logic, Automata and Games 2016

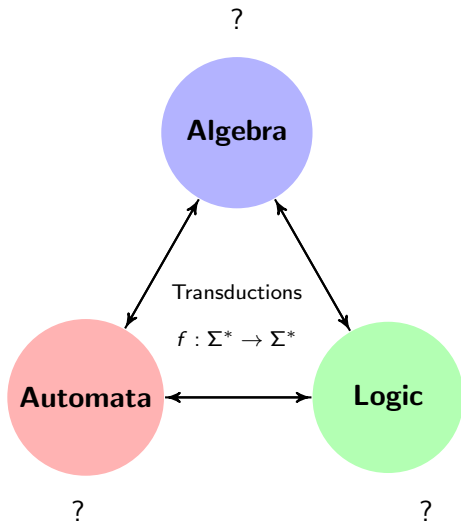
# Trinity for Regular Languages



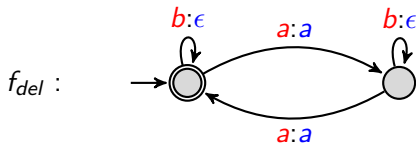
# Trinity for Regular Languages



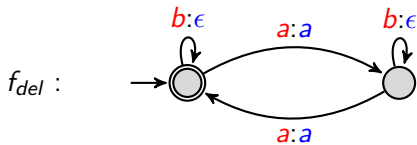
# Objective of the talk



# Automata for transductions: transducers

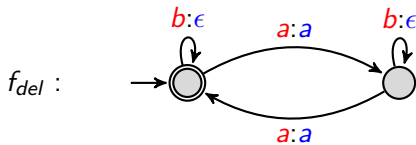


# Automata for transductions: transducers



$aabaa \mapsto aaaa$

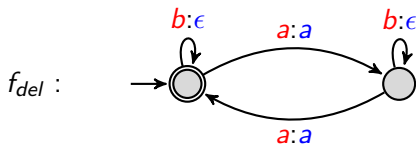
# Automata for transductions: transducers



$aabaa \mapsto aaaa$

$aaba \mapsto \text{undefined}$

# Automata for transductions: transducers



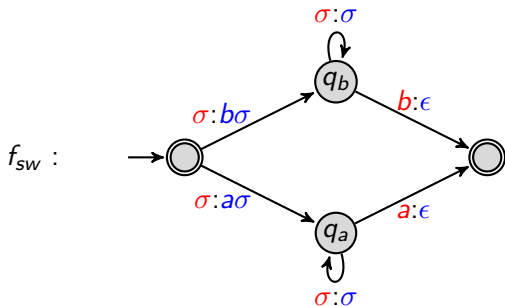
$aabaa \mapsto aaaa$

$aaba \mapsto \text{undefined}$

$\text{dom}(f_{del}) = \text{'even number of } a \text{'}$

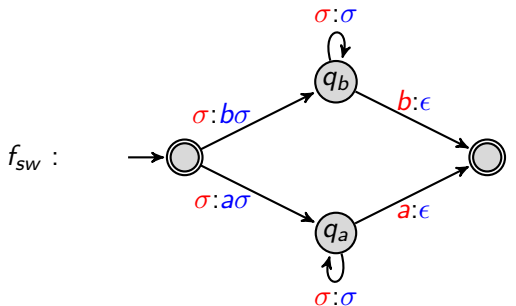


# Automata for transductions: transducers



for all  $\sigma \in \Sigma$

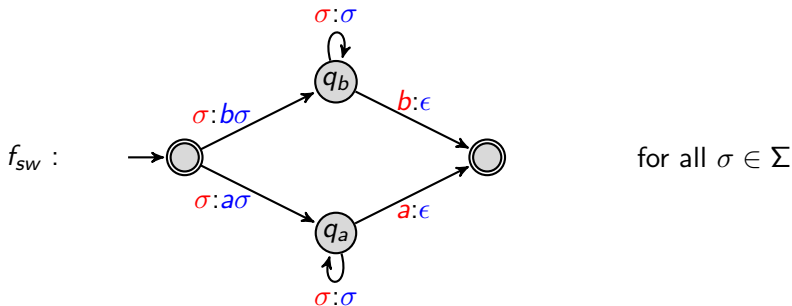
# Automata for transductions: transducers



for all  $\sigma \in \Sigma$

$babaa \mapsto ababa$

# Automata for transductions: transducers



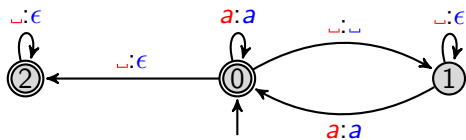
$$babaa \mapsto ababa$$

$$u\sigma \mapsto \sigma u \quad |u| \geq 1$$

input-determinism (aka sequential) < non-determinism

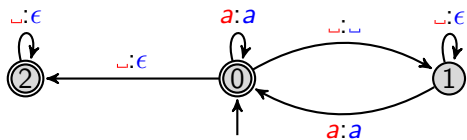
# Automata for transductions: transducers

$\_$  = white space



# Automata for transductions: transducers

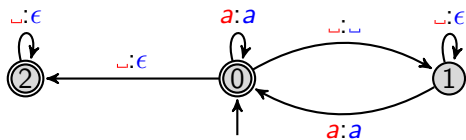
$\_$  = white space



$\_aa\_a\_ \mapsto \_aa\_a$

# Automata for transductions: transducers

$\_$  = white space

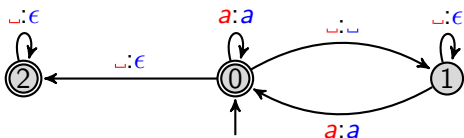


$\_aa\_a\_ \mapsto \_aaa\_$

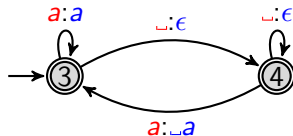
Is non-determinism needed ?

# Automata for transductions: transducers

$\_$  = white space



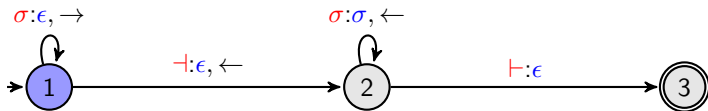
$\_aa\_a\_ \mapsto \_aaa\_$



Is non-determinism needed ? No.

# Automata for transductions: two-way transducers

input  $\vdash$  *s t r e s s e d*  $\vdash$   
 $\uparrow$



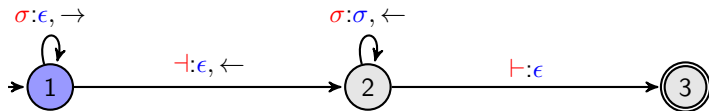
output

$\uparrow$



# Automata for transductions: two-way transducers

input  $\vdash$  s t r e s s e d  $\vdash$   
 $\uparrow$



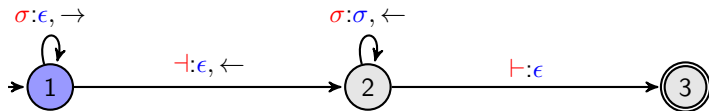
output

$\uparrow$

# Automata for transductions: two-way transducers

input  $\vdash$  s t r e s s e d  $\vdash$

^

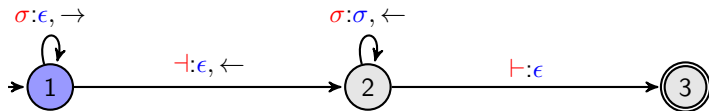


output

^

# Automata for transductions: two-way transducers

input  $\vdash$  s t r e s s e d  $\vdash$   
 $\uparrow$

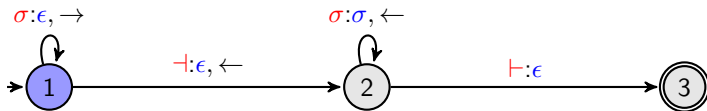


output

$\uparrow$

# Automata for transductions: two-way transducers

input  $\vdash$  s t r e s s e d  $\vdash$

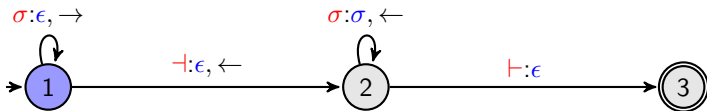


output



# Automata for transductions: two-way transducers

input  $\vdash$  s t r e s s e d  $\vdash$

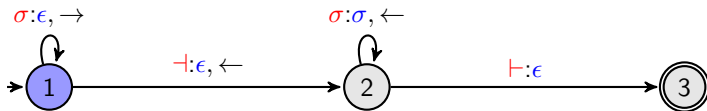


output



# Automata for transductions: two-way transducers

input  $\vdash$  s t r e s s e d  $\vdash$

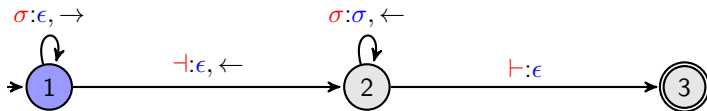


output

$\blacktriangle$

# Automata for transductions: two-way transducers

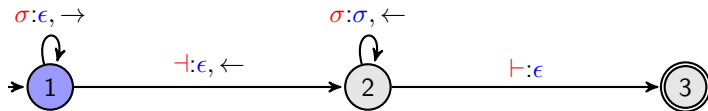
input  $\vdash$  s t r e s s e d  $\vdash$   
▲



output  
▲

# Automata for transductions: two-way transducers

input  $\vdash$  s t r e s s e d  $\vdash$   
▲

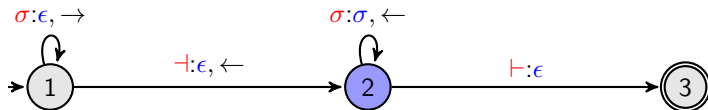


output  
▲



# Automata for transductions: two-way transducers

input  $\vdash$  s t r e s s e d  $\vdash$   
▲

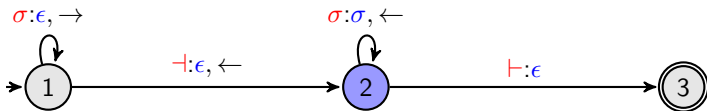


output

▲

# Automata for transductions: two-way transducers

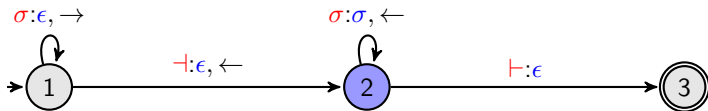
input  $\vdash$  *s t r e s s e d*  $\vdash$   
▲



output *d*  
▲

# Automata for transductions: two-way transducers

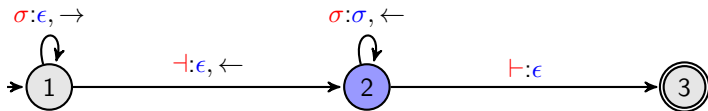
input  $\vdash$  *s t r e s s e d*  $\vdash$   
▲



output *d e*  
▲

# Automata for transductions: two-way transducers

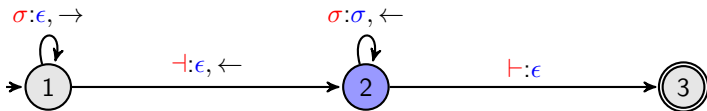
input  $\vdash$  *s* *t* *r* *e* *s* *s* *e* *d*  $\vdash$   
▲



output *d* *e* *s*  
▲

# Automata for transductions: two-way transducers

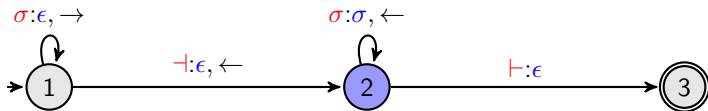
input  $\vdash$  s t r e s s e d  $\vdash$   
 $\uparrow$



output d e s s  
 $\uparrow$

# Automata for transductions: two-way transducers

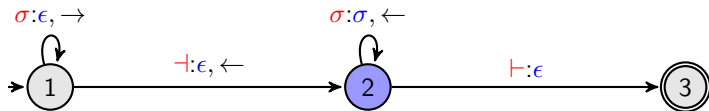
input  $\vdash$  s t r e s s e d  $\vdash$   
 $\uparrow$



output d e s s e  
 $\uparrow$

# Automata for transductions: two-way transducers

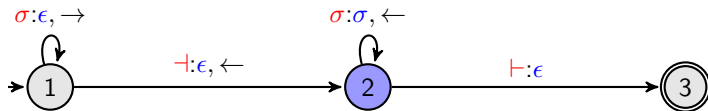
input  $\vdash$  s t r e s s e d  $\vdash$   
▲



output d e s s e r  
▲

# Automata for transductions: two-way transducers

input  $\vdash$  *s t r e s s e d*  $\vdash$   
 $\uparrow$

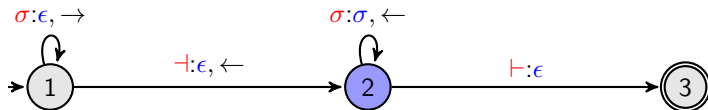


output *d e s s e r t*  
 $\uparrow$



# Automata for transductions: two-way transducers

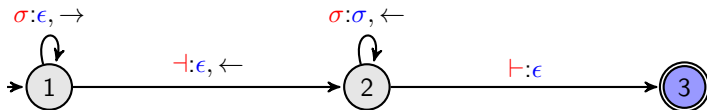
input  $\vdash$  s t r e s s e d  $\vdash$   
 $\blacktriangle$



output d e s s e r t s  
 $\blacktriangle$

# Automata for transductions: two-way transducers

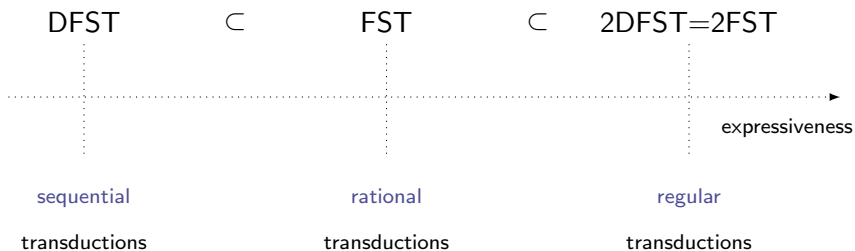
input  $\vdash$  s t r e s s e d  $\vdash$   
 $\blacktriangle$



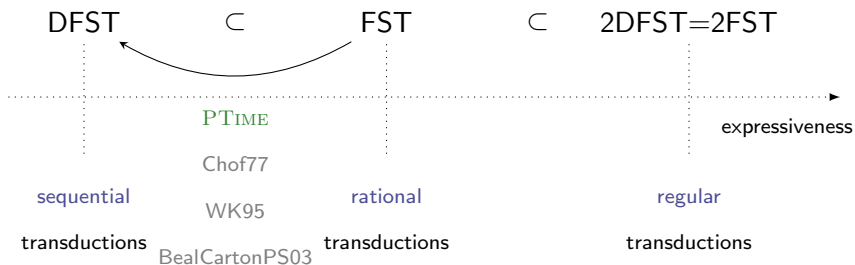
output d e s s e r t s  
 $\blacktriangle$



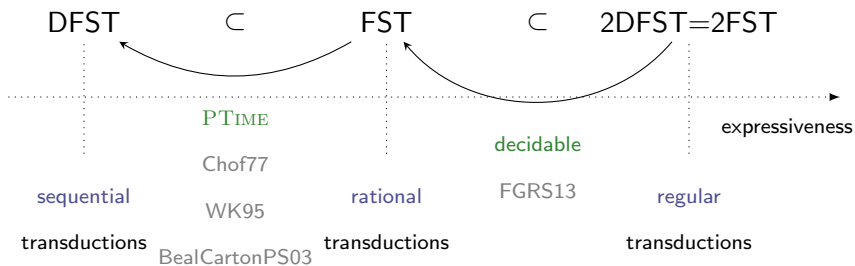
# Landscape of Transducer Classes



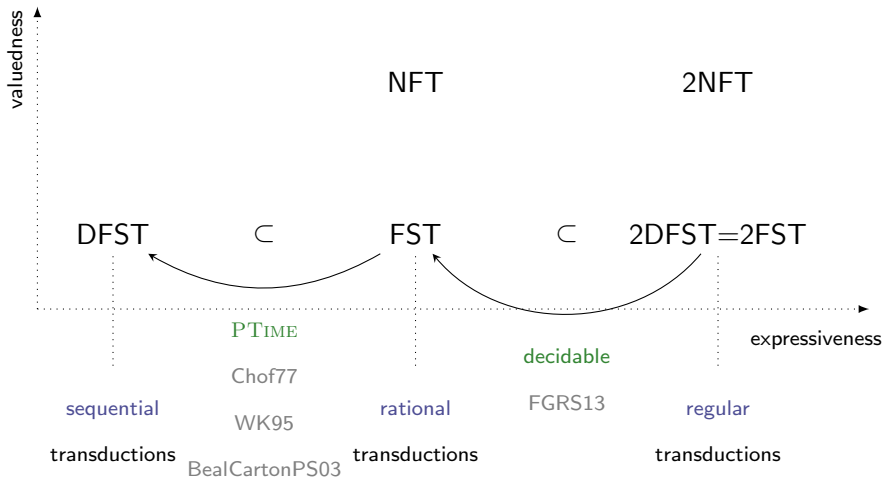
# Landscape of Transducer Classes



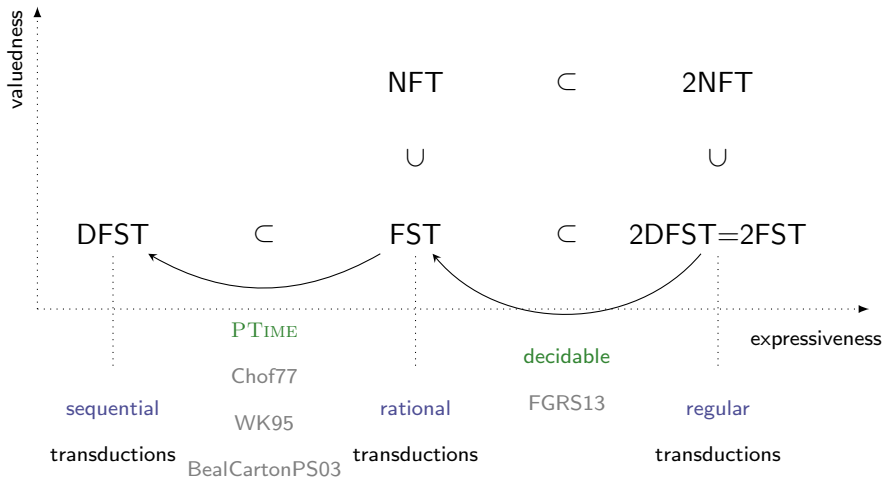
# Landscape of Transducer Classes



# Landscape of Transducer Classes

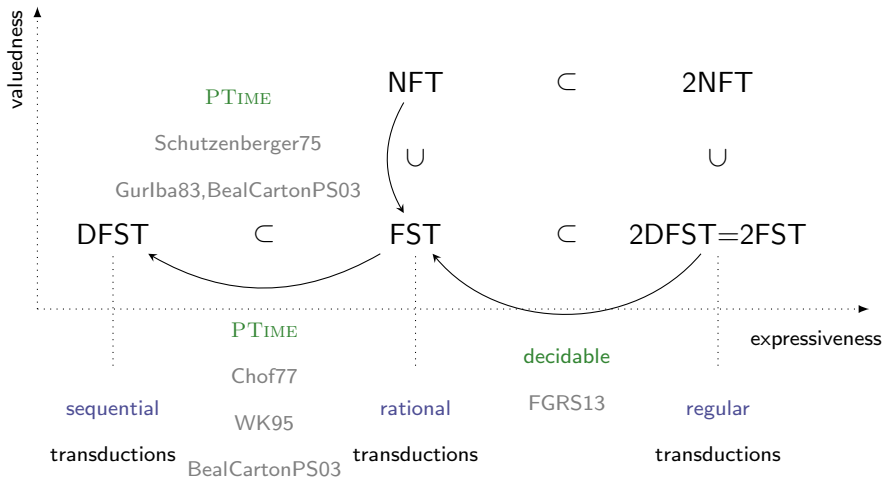


# Landscape of Transducer Classes

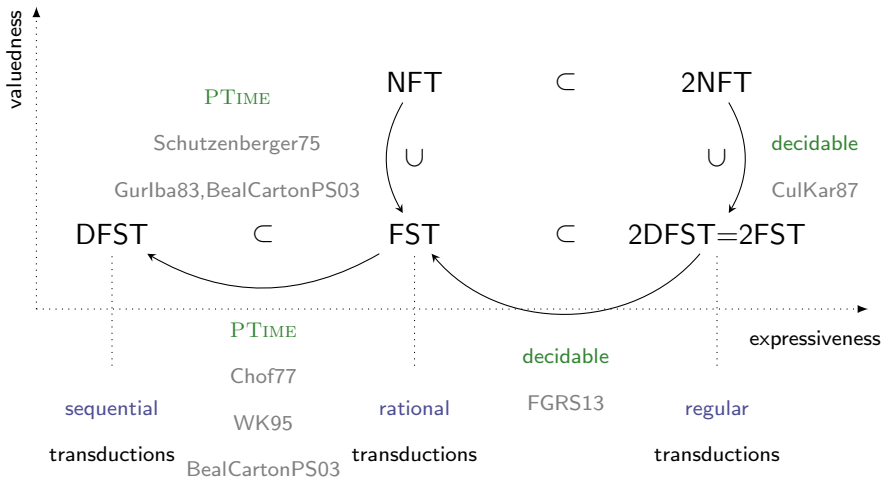




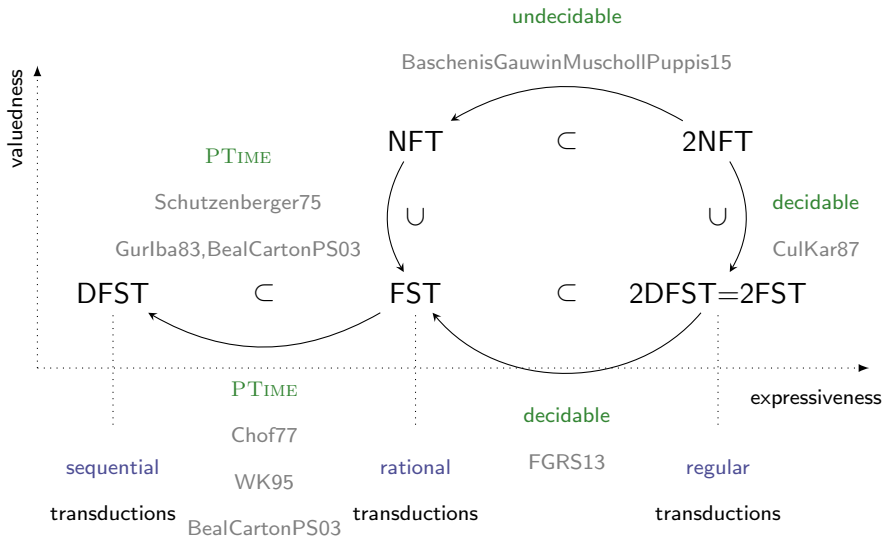
# Landscape of Transducer Classes



# Landscape of Transducer Classes



# Landscape of Transducer Classes



# (Courcelle) MSO Transformations

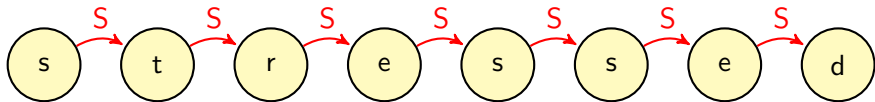
*“interpreting the output structure in the input structure”*

- output predicates defined by MSO[S] formulas interpreted over the input structure

# (Courcelle) MSO Transformations

*“interpreting the output structure in the input structure”*

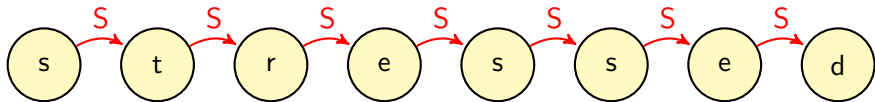
- output predicates defined by  $\text{MSO}[S]$  formulas interpreted over the input structure



# (Courcelle) MSO Transformations

*“interpreting the output structure in the input structure”*

- output predicates defined by MSO[S] formulas interpreted over the input structure



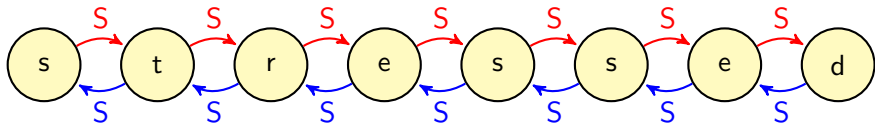
$$\phi_S(x, y) \equiv S(y, x)$$

$$\phi_\sigma(x) \equiv \sigma(x)$$

# (Courcelle) MSO Transformations

*“interpreting the output structure in the input structure”*

- output predicates defined by MSO[S] formulas interpreted over the input structure



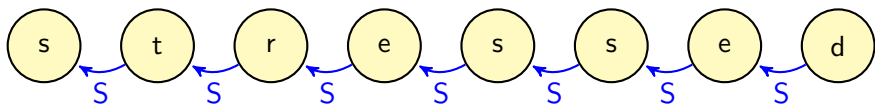
$$\phi_S(x, y) \equiv S(y, x)$$

$$\phi_\sigma(x) \equiv \sigma(x)$$

# (Courcelle) MSO Transformations

*“interpreting the output structure in the input structure”*

- output predicates defined by MSO[S] formulas interpreted over the input structure



$$\phi_S(x, y) \equiv S(y, x)$$

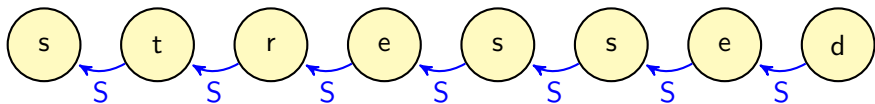
$$\phi_\sigma(x) \equiv \sigma(x)$$



# (Courcelle) MSO Transformations

*“interpreting the output structure in the input structure”*

- output predicates defined by MSO[S] formulas interpreted over the input structure



$$\phi_S(x, y) \equiv S(y, x)$$

$$\phi_\sigma(x) \equiv \sigma(x)$$

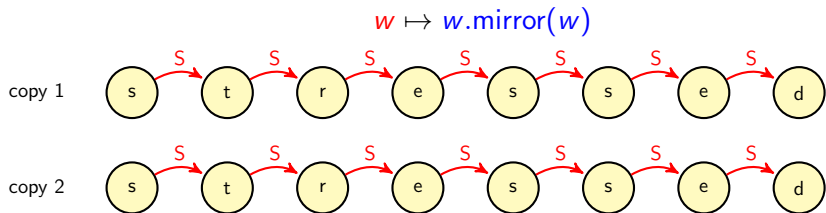
# (Courcelle) MSO Transformations

- input structure can be copied a fixed number of times:

$$w \mapsto w.\text{mirror}(w)$$

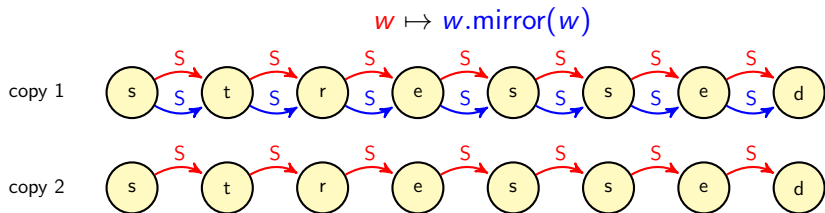
# (Courcelle) MSO Transformations

- input structure can be copied a fixed number of times:



# (Courcelle) MSO Transformations

- input structure can be copied a fixed number of times:

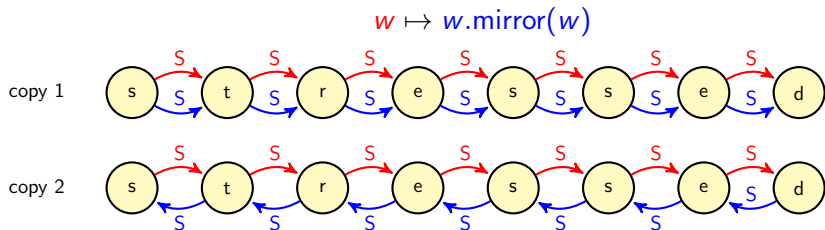


## Formulas

**copy 1:**  $\phi_S^1(x, y) \equiv S(x, y)$

# (Courcelle) MSO Transformations

- input structure can be copied a fixed number of times:



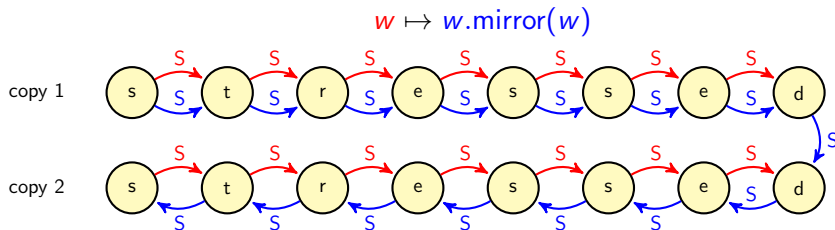
## Formulas

**copy 1:**  $\phi_S^1(x, y) \equiv S(x, y)$

**copy 2:**  $\phi_S^2(x, y) \equiv S(y, x)$

# (Courcelle) MSO Transformations

- input structure can be copied a fixed number of times:



## Formulas

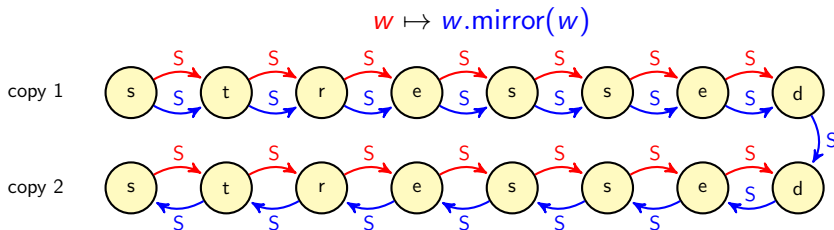
$$\text{copy 1: } \phi_S^1(x, y) \equiv S(x, y)$$

$$\text{copy 2: } \phi_S^2(x, y) \equiv S(y, x)$$

$$\text{copy 1 to copy 2: } \phi_S^{1 \rightarrow 2}(x, y) \equiv x = y \wedge \text{last}(x)$$

# (Courcelle) MSO Transformations

- input structure can be copied a fixed number of times:



## Formulas

$$\text{copy 1: } \phi_S^1(x, y) \equiv S(x, y)$$

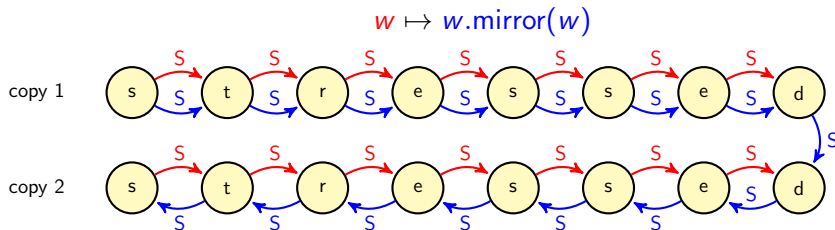
$$\text{copy 2: } \phi_S^2(x, y) \equiv S(y, x)$$

$$\text{copy 1 to copy 2: } \phi_S^{1 \rightarrow 2}(x, y) \equiv x = y \wedge \text{last}(x)$$

$$\text{copy 2 to copy 1: } \phi_S^{2 \rightarrow 1}(x, y) \equiv \perp$$

# (Courcelle) MSO Transformations

- input structure can be copied a fixed number of times:



## Formulas

**copy 1:**  $\phi_S^1(x, y) \equiv S(x, y)$

**copy 2:**  $\phi_S^2(x, y) \equiv S(y, x)$

**copy 1 to copy 2:**  $\phi_S^{1 \rightarrow 2}(x, y) \equiv x = y \wedge last(x)$

**copy 2 to copy 1:**  $\phi_S^{2 \rightarrow 1}(x, y) \equiv \perp$

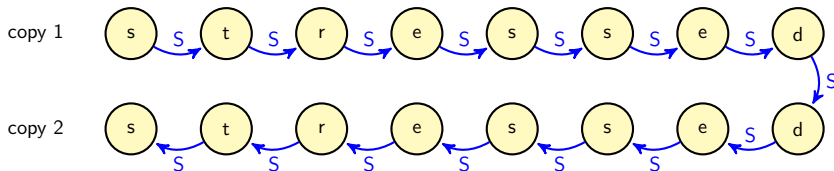
**for all copies  $i$ :**  $\phi_\sigma^i(x) \equiv \sigma(x)$



# (Courcelle) MSO Transformations

- input structure can be copied a fixed number of times:

$$w \mapsto w.\text{mirror}(w)$$



## Formulas

**copy 1:**  $\phi_S^1(x, y) \equiv S(x, y)$

**copy 2:**  $\phi_S^2(x, y) \equiv S(y, x)$

**copy 1 to copy 2:**  $\phi_S^{1 \rightarrow 2}(x, y) \equiv x = y \wedge \text{last}(x)$

**copy 2 to copy 1:**  $\phi_S^{2 \rightarrow 1}(x, y) \equiv \perp$

**for all copies  $i$ :**  $\phi_\sigma^i(x) \equiv \sigma(x)$

# Büchi Theorems for Word Transductions

## Theorem (Engelfriet, Hoogeboom, 01)

Let  $f : \Sigma^* \rightarrow \Sigma^*$ . The following are equivalent:

- 1  $f$  is definable by a deterministic two-way transducer
- 2  $f$  is MSO-definable.

# Büchi Theorems for Word Transductions

## Theorem (Engelfriet, Hoogeboom, 01)

Let  $f : \Sigma^* \rightarrow \Sigma^*$ . The following are equivalent:

- 1  $f$  is definable by a deterministic two-way transducer
- 2  $f$  is MSO-definable.

**Consequence** Equivalence is decidable for MSO-transducers.

# Büchi Theorems for Word Transductions

## Theorem (Engelfriet, Hoogeboom, 01)

Let  $f : \Sigma^* \rightarrow \Sigma^*$ . The following are equivalent:

- 1  $f$  is definable by a deterministic two-way transducer
- 2  $f$  is MSO-definable.

**Consequence** Equivalence is decidable for MSO-transducers.

## Theorem (Bojanczyk 14, F. 15)

Let  $f : \Sigma^* \rightarrow \Sigma^*$ . The following are equivalent:

- 1  $f$  is definable by a (one-way) transducer
- 2  $f$  is definable in order-preserving MSO

Order-preserving MSO:  $\phi_S^{i,j}(x, y) \models x \preceq y$ .

# Myhill-Nerode congruence for $L \subseteq \Sigma^*$

- $u \sim_L v$  if: for all  $w \in \Sigma^*$ ,  $uw \in L$  iff  $vw \in L$
- $u$  and  $v$  have the same “effect” on continuations  $w$
- **Myhill-Nerode’s Thm:**  $L$  is regular iff  $\Sigma^*/\sim_L$  is finite
- canonical (and minimal) deterministic automaton for  $L$ ,  $\Sigma^*/\sim_L$  as set of states

# Myhill-Nerode congruence for $L \subseteq \Sigma^*$

- $u \sim_L v$  if: for all  $w \in \Sigma^*$ ,  $uw \in L$  iff  $vw \in L$
- $u$  and  $v$  have the same “effect” on continuations  $w$
- **Myhill-Nerode’s Thm:**  $L$  is regular iff  $\Sigma^*/\sim_L$  is finite
- canonical (and minimal) deterministic automaton for  $L$ ,  $\Sigma^*/\sim_L$  as set of states

## Goal

Extend Myhill-Nerode’s theorem to classes of transductions

# Sequential transductions (Choffrut)

Refinement of the MN congruence.

Two ideas

- 1 produce asap:  $F(u) = LCP\{f(uw) \mid uw \in \text{dom}(f)\}$

# Sequential transductions (Choffrut)

Refinement of the MN congruence.

## Two ideas

- ① produce asap:  $F(u) = LCP\{f(uw) \mid uw \in \text{dom}(f)\}$
- ②  $u \sim_f v$  if
  - ①  $u \sim_{\text{dom}(f)} v$
  - ②  $F(u)^{-1}f(uw) = F(v)^{-1}f(vw) \quad \forall w \in u^{-1}\text{dom}(f)$

“ $u$  and  $v$  have the same effect on continuations  $w$  w.r.t. domain membership and produced outputs”



# Sequential transductions (Choffrut)

Refinement of the MN congruence.

## Two ideas

- ① produce asap:  $F(u) = LCP\{f(uw) \mid uw \in \text{dom}(f)\}$
- ②  $u \sim_f v$  if
  - ①  $u \sim_{\text{dom}(f)} v$
  - ②  $F(u)^{-1}f(uw) = F(v)^{-1}f(vw) \quad \forall w \in u^{-1}\text{dom}(f)$

“ $u$  and  $v$  have the same effect on continuations  $w$  w.r.t. domain membership and produced outputs”

## Theorem (Choffrut)

*$f$  is sequential iff  $\sim_f$  has finite index*

$\sim_f$  is a right congruence  $\rightsquigarrow$  canonical and minimal transducer !

Transitions:  $[u] \xrightarrow{\sigma | F(u)^{-1}F(u\sigma)} [u\sigma]$

# Rational transductions are almost sequential

- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .

*abbaaaabbbbab*

# Rational transductions are almost sequential

- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .

*abbaaaabbbbab*<sup>ε</sup>

# Rational transductions are almost sequential

- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .

$abbaaaabbbbab$

# Rational transductions are almost sequential

- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .

$a b b a a a a b b b b a b$

$b b \epsilon$

# Rational transductions are almost sequential

- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .

$a b b a a a b b b a b$   
                                   $b b b \epsilon$

# Rational transductions are almost sequential

- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .

$a b b a a a a b b b b a b$   
 $\quad \quad \quad \quad \quad b b b b \epsilon$

# Rational transductions are almost sequential

- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .

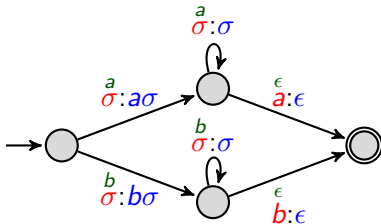
$b b b b b b b b b b b \epsilon$   
 $a b b a a a a b b b b a b$



# Rational transductions are almost sequential

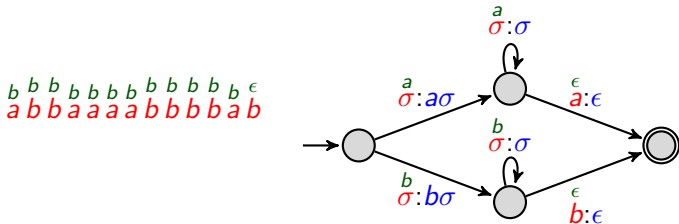
- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .

$b\ b\ b\ b\ b\ b\ b\ b\ b\ b\ b\ b\ \epsilon$   
 $a\ b\ b\ a\ a\ a\ a\ b\ b\ b\ b\ a\ b$



# Rational transductions are almost sequential

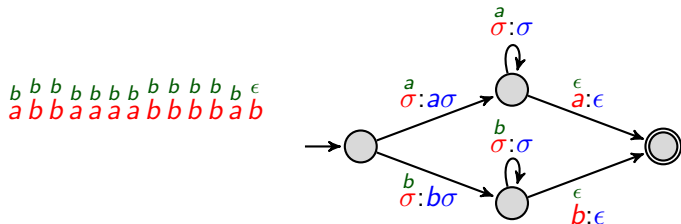
- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .



- look-ahead information:  $\mathcal{L} : \Sigma^* \rightarrow \mathcal{I}$
- $f[\mathcal{L}]$ :  $f$  with input words extended with look-ahead information

# Rational transductions are almost sequential

- $f_{sw} : u\sigma \mapsto \sigma u$  is not sequential
- but sequential modulo *look-ahead information*  $\mathcal{I} = \{a, b, \epsilon\}$ .



- look-ahead information:  $\mathcal{L} : \Sigma^* \rightarrow \mathcal{I}$
- $f[\mathcal{L}]$ :  $f$  with input words extended with look-ahead information

## Theorem (Elgot, Mezei, 65)

$f$  is rational iff  $f[\mathcal{L}]$  is sequential, for some finite look-ahead information  $\mathcal{L}$  computable by a right sequential transducer.

Original statement:  $RAT = SEQ \circ RightSEQ$ .

# A canonical look-ahead

Identify suffixes with a 'bounded' effect on prefixes.

## Equivalent suffixes

- $u \equiv_f v$  if  $\{d(f(wu), f(wv)) \mid wu, wv \in \text{dom}(f)\}$  is finite<sup>a</sup>.

# A canonical look-ahead

Identify suffixes with a 'bounded' effect on prefixes.

## Equivalent suffixes

- $u \equiv_f v$  if  $\{d(f(wu), f(wv)) \mid wu, wv \in \text{dom}(f)\}$  is finite<sup>a</sup>.
- $\equiv_f$  is a left congruence

# A canonical look-ahead

Identify suffixes with a 'bounded' effect on prefixes.

## Equivalent suffixes

- $u \equiv_f v$  if  $\{d(f(wu), f(wv)) \mid wu, wv \in \text{dom}(f)\}$  is finite<sup>a</sup>.
- $\equiv_f$  is a left congruence
- look-ahead: return the class of the suffix.

---


$$^a d(\alpha, \beta) = |\alpha| + |\beta| - 2|\text{lcp}(\alpha, \beta)|.$$

**Ex:** For  $f_{sw}$ ,  $\Sigma^*/\equiv = \{\{ua \mid u \in \Sigma^*\}, \{ub \mid u \in \Sigma^*\}, \{\epsilon\}\}$ .

# A canonical look-ahead

Identify suffixes with a 'bounded' effect on prefixes.

## Equivalent suffixes

- $u \equiv_f v$  if  $\{d(f(wu), f(wv)) \mid wu, wv \in \text{dom}(f)\}$  is finite<sup>a</sup>.
- $\equiv_f$  is a left congruence
- look-ahead: return the class of the suffix.

$$^a d(\alpha, \beta) = |\alpha| + |\beta| - 2|\text{lcp}(\alpha, \beta)|.$$

**Ex:** For  $f_{sw}$ ,  $\Sigma^*/\equiv = \{\{ua \mid u \in \Sigma^*\}, \{ub \mid u \in \Sigma^*\}, \{\epsilon\}\}$ .

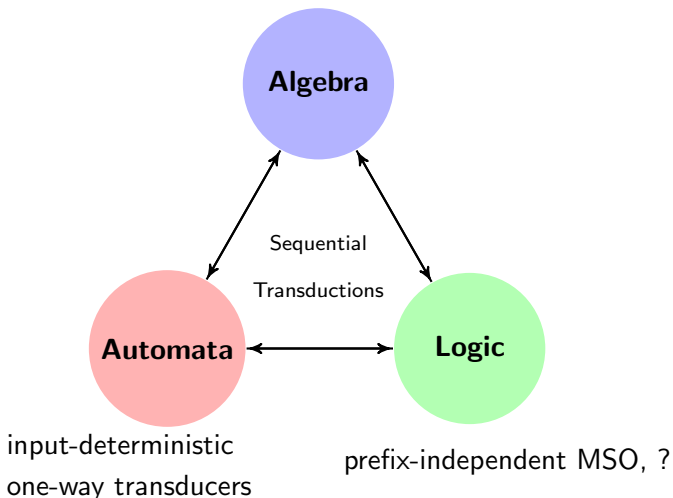
## Theorem (Reutenauer, Schützenberger, 91)

*The following are equivalent:*

- $f$  is rational
- $\equiv_f$  has finite index and  $f[\equiv_f]$  is sequential
- $\equiv_f$  and  $\sim_{f[\equiv_f]}$  have finite index.

# Summary: sequential transductions

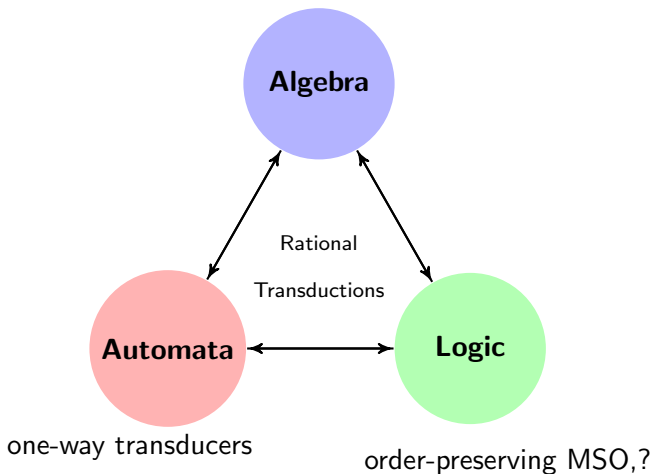
finiteness of  $\sim_f$  (Choffrut)



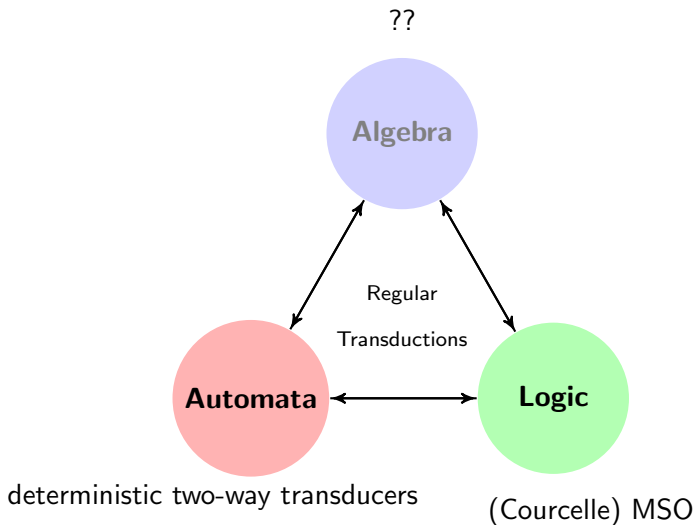


# Summary: rational transductions

finiteness of  $\equiv_f$  and  $\sim_f[\equiv_f]$  (Reutenauer, Schützenberger)

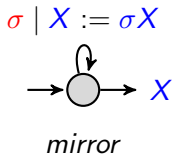


# Summary: regular transductions



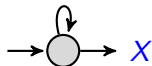
# Transducers with Registers $FST_{re}$ (Alur, Cerny, 10)

- deterministic one-way
- register updates:  
 $X := YZ, X := u$

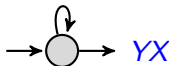


# Transducers with Registers $FST_{re}$ (Alur, Cerny, 10)

- deterministic one-way
- register updates:  
 $X := YZ, X := u$

 $\sigma \mid X := \sigma X$ 


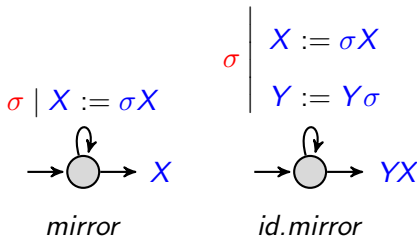
*mirror*

 $\sigma \mid \begin{array}{l} X := \sigma X \\ Y := Y\sigma \end{array}$ 


*id.mirror*

# Transducers with Registers $FST_{re}$ (Alur, Cerny, 10)

- deterministic one-way
- register updates:  
 $X := YZ, X := u$



## Results

- MSO-equivalent if copyless updates (Alur, Cerny, 10)
- decidable equivalence problem (F., Reynier)  $\sim$  HDT0L

# Recent definability problems for functions

Given a transduction  $f \in \mathcal{S}$ , does  $f \in \mathcal{T}$  ?

# Recent definability problems for functions

Given a transduction  $f \in \mathcal{S}$ , does  $f \in \mathcal{T}$  ?

$\mathcal{S}$	repr	$\mathcal{T}$	status	reference
SEQ	.	$AC^0$	decidable	Cadilhac,Krebs,Ludwig,Paperman,15

# Recent definability problems for functions

Given a transduction  $f \in \mathcal{S}$ , does  $f \in \mathcal{T}$  ?

$\mathcal{S}$	repr	$\mathcal{T}$	status	reference
SEQ	.	$AC^0$	decidable	Cadilhac, Krebs, Ludwig, Paperman, 15
RAT	bimachine	opFO= <b>A</b> p-FST	PSPACE-c	Lhote, F, Gauwin, submitted



# Recent definability problems for functions

Given a transduction  $f \in \mathcal{S}$ , does  $f \in \mathcal{T}$  ?

$\mathcal{S}$	repr	$\mathcal{T}$	status	reference
SEQ	.	$AC^0$	decidable	Cadilhac, Krebs, Ludwig, Paperman, 15
RAT	bimachine	opFO= <b>A</b> p-FST	PSPACE-c	Lhote, F, Gauwin, submitted
RAT	.	<b>V</b> -FST	decidable	Lhote, F, Gauwin, 16

# Recent definability problems for functions

Given a transduction  $f \in \mathcal{S}$ , does  $f \in \mathcal{T}$  ?

$\mathcal{S}$	repr	$\mathcal{T}$	status	reference
SEQ	.	$AC^0$	decidable	Cadilhac,Krebs,Ludwig,Paperman,15
RAT	bimachine	opFO= <b>A</b> p-FST	PSpace-c	Lhote, F, Gauwin, submitted
RAT	.	<b>V</b> -FST	decidable	Lhote, F, Gauwin,16
REG	2FST	RAT	decidable	F, Gauwin, Reynier, Servais,13

# Recent definability problems for functions

Given a transduction  $f \in \mathcal{S}$ , does  $f \in \mathcal{T}$  ?

$\mathcal{S}$	repr	$\mathcal{T}$	status	reference
SEQ	.	$AC^0$	decidable	Cadilhac,Krebs,Ludwig,Paperman,15
RAT	bimachine	opFO= <b>A</b> p-FST	PSpace-c	Lhote, F, Gauwin, submitted
RAT	.	<b>V</b> -FST	decidable	Lhote, F, Gauwin,16
REG	2FST	RAT	decidable	F, Gauwin, Reynier, Servais,13
SWEEP	2FST	$k$ -SWEEP	ExpSpace	Baschenis,Gauwin,Muscholl,Puppis,16

# Recent definability problems for functions

Given a transduction  $f \in \mathcal{S}$ , does  $f \in \mathcal{T}$  ?

$\mathcal{S}$	repr	$\mathcal{T}$	status	reference
SEQ	.	$AC^0$	decidable	Cadilhac,Krebs,Ludwig,Paperman,15
RAT	bimachine	opFO= <b>A</b> p-FST	PSpace-c	Lhote, F, Gauwin, submitted
RAT	.	<b>V</b> -FST	decidable	Lhote, F, Gauwin,16
REG	2FST	RAT	decidable	F, Gauwin, Reynier, Servais,13
SWEEP	2FST	$k$ -SWEEP	ExpSpace	Baschenis,Gauwin,Muscholl,Puppis,16
REG	2FST	FO	?	

# Recent definability problems for functions

Given a transduction  $f \in \mathcal{S}$ , does  $f \in \mathcal{T}$  ?

$\mathcal{S}$	repr	$\mathcal{T}$	status	reference
SEQ	.	$AC^0$	decidable	Cadilhac,Krebs,Ludwig,Paperman,15
RAT	bimachine	opFO= <b>Ap</b> -FST	PSpace-c	Lhote, F, Gauwin, submitted
RAT	.	<b>V</b> -FST	decidable	Lhote, F, Gauwin,16
REG	2FST	RAT	decidable	F, Gauwin, Reynier, Servais,13
SWEEP	2FST	$k$ -SWEEP	ExpSpace	Baschenis,Gauwin,Muscholl,Puppis,16
REG	2FST	FO	?	
FO	.	<b>Ap</b> -2FST	iff	Carton, Dartois,15

# Recent definability problems for functions

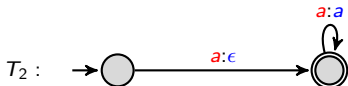
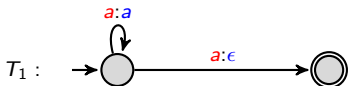
Given a transduction  $f \in \mathcal{S}$ , does  $f \in \mathcal{T}$  ?

$\mathcal{S}$	repr	$\mathcal{T}$	status	reference
SEQ	.	$AC^0$	decidable	Cadilhac, Krebs, Ludwig, Paperman, 15
RAT	bimachine	opFO= <b>Ap</b> -FST	PSpace-c	Lhote, F, Gauwin, submitted
RAT	.	<b>V</b> -FST	decidable	Lhote, F, Gauwin, 16
REG	2FST	RAT	decidable	F, Gauwin, Reynier, Servais, 13
SWEEP	2FST	$k$ -SWEEP	ExpSpace	Baschenis, Gauwin, Muscholl, Puppis, 16
REG	2FST	FO	?	
FO	.	<b>Ap</b> -2FST	<i>iff</i>	Carton, Dartois, 15
				Dartois, Jecker, Reynier, 16
FO	.	<b>Ap</b> -FST <sub>re</sub>	<i>iff</i>	F, Trivedi, Krishna, 14

# Origin Information

## Asynchronicity

- make reasoning about transducers difficult
- equivalence problem is undecidable for NFT



# Origin Information

## Asynchronicity

- make reasoning about transducers difficult
- equivalence problem is undecidable for NFT



## Origin semantics (Bojanczyk, 14)

Reintroduce synchronicity:  $\Sigma^* \rightarrow (\Sigma^* \times (\mathbb{N} \rightarrow \mathbb{N}))$





# Origin Information

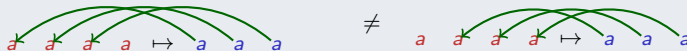
## Asynchronicity

- make reasoning about transducers difficult
- equivalence problem is undecidable for NFT



## Origin semantics (Bojanczyk, 14)

Reintroduce synchronicity:  $\Sigma^* \rightarrow (\Sigma^* \times (\mathbb{N} \rightarrow \mathbb{N}))$



## Results

- machine-independent characterization of regular transductions with origin and first-order definability (Bojanczyk, 14)
- relaxation of origin semantics & decision problems (F., Jecker, Löding, Winter, 16)

# Other works

- regular combinators (Alur, Freilich, Raghothaman, 14)
- variants of two-way transducers (Guillon, Choffrut, 14,15,16), (Carton, 12) (McKenzie, Schwentick, Thérien, Vollmer, 06)
- extensions with non-determinism

# SIGLOG News 9th



## Transducers, Logic and Algebra for Functions of Finite Words

Emmanuel Filiot, Université Libre de Bruxelles  
and Pierre-Alain Reynier, Aix-Marseille Université

The robust theory of regular languages is based on three important pillars: computation (automata) and algebra. In this paper, we survey old and recent results on extensions of these pillars to functions of words to words. We consider two important classes of word functions, the rational and regular functions respectively defined by one-way and two-way automata with output words, called transducers.

... between computation, mathematical logic, and algebra of finite words. The class of regular languages is contained in the class of regular functions. The class of regular functions is strictly larger than the class of regular languages [Büchi 1960; Elgot 1961]. While an automaton is a monoid, a canonical monoid, a canonical monoid (1). While an

