

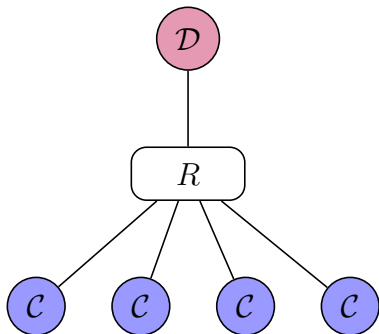
# On Parameterized Verification of Asynchronous Shared-Memory Pushdown Systems

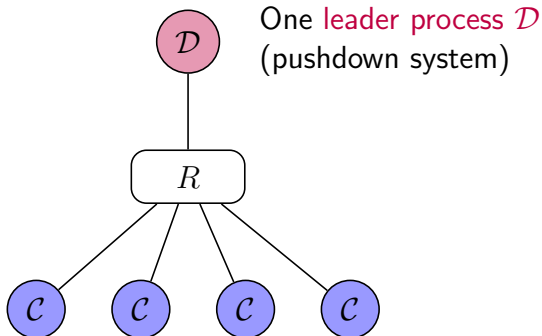
**Marie Fortin**<sup>1</sup>   Anca Muscholl<sup>2</sup>   Igor Walukiewicz<sup>2</sup>

<sup>1</sup>LSV, ENS Cachan

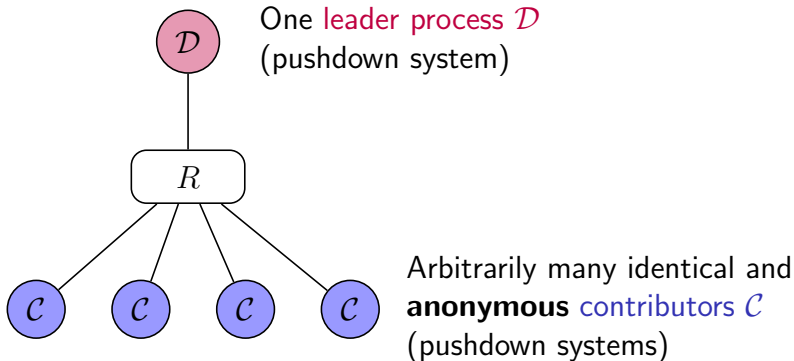
<sup>2</sup>LaBRI, University of Bordeaux

Highlights 2016, Brussels

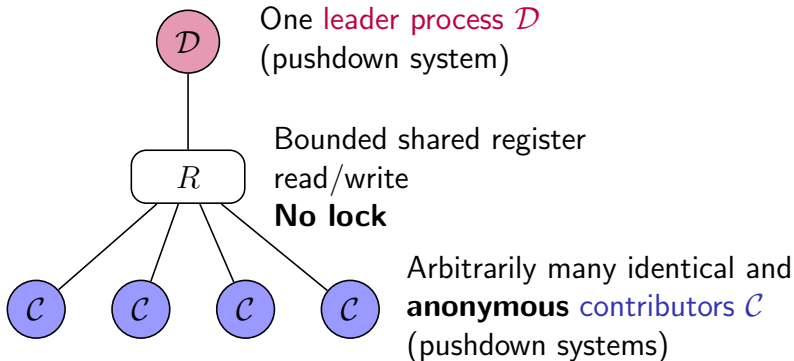
$(\mathcal{C}, \mathcal{D})$ -systems

$(\mathcal{C}, \mathcal{D})$ -systems

# $(\mathcal{C}, \mathcal{D})$ -systems



# $(\mathcal{C}, \mathcal{D})$ -systems



# Previous Work

# Previous Work

## Reachability

Is there a run of the  $(\mathcal{C}, \mathcal{D})$ -system where the leader performs a special action  $\top$ , for some number of contributors?

[Hague, 2011]  $\text{EXPSPACE}$

[Esparza, Ganty, Majumdar, 2013]  $\text{PSPACE-complete}$

[La Torre, Muscholl, Walukiewicz, 2015] Generalization

## Previous Work

### Reachability

Is there a run of the  $(\mathcal{C}, \mathcal{D})$ -system where the leader performs a special action  $\top$ , for some number of contributors?

[Hague, 2011]  $\text{EXPSPACE}$

[Esparza, Ganty, Majumdar, 2013]  $\text{PSPACE-complete}$

[La Torre, Muscholl, Walukiewicz, 2015] Generalization

### Repeated reachability

Is there a run of the  $(\mathcal{C}, \mathcal{D})$ -system where the leader performs  $\top$  infinitely often, for some number of contributors?

[Durand-Gasselín, Esparza, Ganty, Majumdar, 2015]

$\text{PSPACE-hard}$  and in  $\text{NEXPTIME}$



# Repeated reachability

# Repeated reachability

## Theorem

The repeated reachability problem is PSPACE-complete.

# Repeated reachability

## Theorem

The repeated reachability problem is PSPACE-complete.

[Durand-Gasselín, Esparza, Ganty, Majumdar, 2015]:

- ▷ Reduction to the case of finite-state contributors, by bounding the stacks of the contributors
- ▷ NP in the case of finite-state contributors  $\rightarrow$  NEXPTIME for pushdown contributors

# Repeated reachability

## Theorem

The repeated reachability problem is PSPACE-complete.

[Durand-Gasselín, Esparza, Ganty, Majumdar, 2015]:

- ▷ Reduction to the case of finite-state contributors, by bounding the stacks of the contributors
- ▷ NP in the case of finite-state contributors  $\rightarrow$  NEXPTIME for pushdown contributors

We re-use the reduction to finite-state contributors, but change the decision procedure

## Key steps for the PSPACE upper bound

- Look for an ultimately periodic run.

## Key steps for the PSPACE upper bound

- Look for an ultimately periodic run.
- Adapt from finite runs to infinite periodic runs the techniques of [La Torre, Muscholl, Walukiewicz, 2015]:

## Key steps for the PSPACE upper bound

- Look for an ultimately periodic run.
- Adapt from finite runs to infinite periodic runs the techniques of [La Torre, Muscholl, Walukiewicz, 2015]:
  - Define a transition system  $\mathcal{D}^\kappa = \mathcal{D} + \text{capacity}$ : set of values written by the contributors in the register.

**Idea:** if a contributor can produce a value  $g$  once, by adding copies of this contributor we can produce as many  $g$ 's as needed.

## Key steps for the PSPACE upper bound

- Look for an ultimately periodic run.
- Adapt from finite runs to infinite periodic runs the techniques of [La Torre, Muscholl, Walukiewicz, 2015]:
  - Define a transition system  $\mathcal{D}^\kappa = \mathcal{D} + \text{capacity}$ : set of values written by the contributors in the register.

**Idea:** if a contributor can produce a value  $g$  once, by adding copies of this contributor we can produce as many  $g$ 's as needed.

- Define similarly  $\mathcal{C}^\kappa$ . A loop in  $\mathcal{D}^\kappa$  corresponds to a loop in the  $(\mathcal{C}, \mathcal{D})$ -system if each addition to the capacity is **supported** by a loop in  $\mathcal{C}^\kappa$  producing the necessary write.



## Key steps for the PSPACE upper bound

- Look for an ultimately periodic run.
- Adapt from finite runs to infinite periodic runs the techniques of [La Torre, Muscholl, Walukiewicz, 2015]:
  - Define a transition system  $\mathcal{D}^\kappa = \mathcal{D} + \text{capacity}$ : set of values written by the contributors in the register.

**Idea:** if a contributor can produce a value  $g$  once, by adding copies of this contributor we can produce as many  $g$ 's as needed.

- Define similarly  $\mathcal{C}^\kappa$ . A loop in  $\mathcal{D}^\kappa$  corresponds to a loop in the  $(\mathcal{C}, \mathcal{D})$ -system if each addition to the capacity is **supported** by a loop in  $\mathcal{C}^\kappa$  producing the necessary write.
- Replace  $\mathcal{D}^\kappa$  by its downward closure, and look for a supported loop in  $\mathcal{D}^\kappa \downarrow$ : one run of  $\mathcal{D}^\kappa \downarrow + \ell$  runs of  $\mathcal{C}^\kappa$ .

## Key steps for the PSPACE upper bound

- Look for an ultimately periodic run.
- Adapt from finite runs to infinite periodic runs the techniques of [La Torre, Muscholl, Walukiewicz, 2015]:
  - Define a transition system  $\mathcal{D}^\kappa = \mathcal{D} + \text{capacity}$ : set of values written by the contributors in the register.

**Idea:** if a contributor can produce a value  $g$  once, by adding copies of this contributor we can produce as many  $g$ 's as needed.

- Define similarly  $\mathcal{C}^\kappa$ . A loop in  $\mathcal{D}^\kappa$  corresponds to a loop in the  $(\mathcal{C}, \mathcal{D})$ -system if each addition to the capacity is **supported** by a loop in  $\mathcal{C}^\kappa$  producing the necessary write.
- Replace  $\mathcal{D}^\kappa$  by its downward closure, and look for a supported loop in  $\mathcal{D}^\kappa \downarrow$ : one run of  $\mathcal{D}^\kappa \downarrow + \ell$  runs of  $\mathcal{C}^\kappa$ .  
→ Intersection emptiness of  $\ell + 1$  finite automata computable in PSPACE.

# Universal reachability

## Reachability

Is there a run of the  $(\mathcal{C}, \mathcal{D})$ -system where the leader performs a special action  $\top$ , for some number of contributors?

## Repeated reachability

Is there a run of the  $(\mathcal{C}, \mathcal{D})$ -system where the leader performs  $\top$  infinitely often, for some number of contributors?

## Universal reachability

Does the leader perform  $\top$  in all **(finite or infinite) maximal** runs of the  $(\mathcal{C}, \mathcal{D})$ -system, for any number of contributors ?

# Universal reachability

## Motivation

Correctness problems for distributed algorithms: is the outcome correct (does the leader execute  $\top$ ) for an arbitrary number of participants and for every run of the algorithm?

# Universal reachability

## Motivation

Correctness problems for distributed algorithms: is the outcome correct (does the leader execute  $\top$ ) for an arbitrary number of participants and for every run of the algorithm?

## Specificity

We consider finite maximal runs as well as infinite ones

→ deadlock detection

# Universal reachability

## Theorem

The universal reachability problem is  $\text{coNEXPTIME}$ -complete.

# Universal reachability

## Theorem

The universal reachability problem is  $\text{coNEXPTIME}$ -complete.

Is there a maximal run without any occurrence of  $\top$ ?

# Universal reachability

## Theorem

The universal reachability problem is  $\text{coNEXPTIME}$ -complete.

Is there a maximal run without any occurrence of  $\top$ ?

- For infinite runs: reduction to repeated reachability



# Universal reachability

## Theorem

The universal reachability problem is  $\text{coNEXPTIME}$ -complete.

Is there a maximal run without any occurrence of  $\top$ ?

- For infinite runs: reduction to repeated reachability
- For finite runs: use the reduction to the case of finite-state contributors, show that it is  $\text{NP}$ -complete

# Universal reachability

## Theorem

The universal reachability problem is  $\text{coNEXPTIME}$ -complete.

Is there a maximal run without any occurrence of  $\top$ ?

- For infinite runs: reduction to repeated reachability
- For finite runs: use the reduction to the case of finite-state contributors, show that it is  $\text{NP}$ -complete
- $\text{NEXPTIME}$ -hardness: tiling of the  $2^n \times 2^n$  square.

# Generalization

Until now: verification of properties on **leader actions only**.

We consider the verification of regular properties

$\mathcal{P} \subseteq (\Sigma_C \cup \Sigma_D)^* \cup (\Sigma_C \cup \Sigma_D)^\omega$  on both

- finite **and** infinite traces
- leader **and** contributor actions

# Generalization

Until now: verification of properties on **leader actions only**.

We consider the verification of regular properties

$\mathcal{P} \subseteq (\Sigma_C \cup \Sigma_D)^* \cup (\Sigma_C \cup \Sigma_D)^\omega$  on both

- finite **and** infinite traces
- leader **and** contributor actions

## Restriction

**C-expanding properties:** if  $u \in \mathcal{P}$  and  $u'$  is obtained by repeating some contributor actions in  $u$ , then  $u' \in \mathcal{P}$ .

# Main result

## Theorem

The following problem is NEXPTIME-complete:

**Input:** a  $(\mathcal{C}, \mathcal{D})$ -system, and a regular  $\mathcal{C}$ -expanding property  $\mathcal{P} \subseteq (\Sigma_{\mathcal{C}} \cup \Sigma_{\mathcal{D}})^* \cup (\Sigma_{\mathcal{C}} \cup \Sigma_{\mathcal{D}})^\omega$ .

**Question:** Is there a maximal trace of the  $(\mathcal{C}, \mathcal{D})$ -system that belongs to  $\mathcal{P}$  ?

# Main result

## Theorem

The following problem is NEXPTIME-complete:

**Input:** a  $(\mathcal{C}, \mathcal{D})$ -system, and a regular  $\mathcal{C}$ -expanding property  $\mathcal{P} \subseteq (\Sigma_{\mathcal{C}} \cup \Sigma_{\mathcal{D}})^* \cup (\Sigma_{\mathcal{C}} \cup \Sigma_{\mathcal{D}})^\omega$ .

**Question:** Is there a maximal trace of the  $(\mathcal{C}, \mathcal{D})$ -system that belongs to  $\mathcal{P}$  ?

Steps of the proof:

- Reduction to a property on leader actions, by transforming the  $(\mathcal{C}, \mathcal{D})$ -system into one where all contributor actions are reflected in leader writes

# Main result

## Theorem

The following problem is NEXPTIME-complete:

**Input:** a  $(\mathcal{C}, \mathcal{D})$ -system, and a regular  $\mathcal{C}$ -expanding property  $\mathcal{P} \subseteq (\Sigma_{\mathcal{C}} \cup \Sigma_{\mathcal{D}})^* \cup (\Sigma_{\mathcal{C}} \cup \Sigma_{\mathcal{D}})^\omega$ .

**Question:** Is there a maximal trace of the  $(\mathcal{C}, \mathcal{D})$ -system that belongs to  $\mathcal{P}$  ?

Steps of the proof:

- Reduction to a property on leader actions, by transforming the  $(\mathcal{C}, \mathcal{D})$ -system into one where all contributor actions are reflected in leader writes
- Reduction to our previous results
  - Infinite traces: reduction to repeated reachability
  - Finite traces: results about universal reachability

# Summary



# Summary

- We improved the complexity upper bound for repeated reachability from  $\text{NEXPTIME}$  to  $\text{PSPACE}$

# Summary

- We improved the complexity upper bound for repeated reachability from  $\text{NEXPTIME}$  to  $\text{PSPACE}$
- We introduced universal reachability, and showed that it is  $\text{coNEXPTIME}$ -complete

# Summary

- We improved the complexity upper bound for repeated reachability from  $\text{NEXPTIME}$  to  $\text{PSPACE}$
- We introduced universal reachability, and showed that it is  $\text{coNEXPTIME}$ -complete
- Verification of regular  $\mathcal{C}$ -expanding properties is also  $\text{NEXPTIME}$ -complete

# Summary

- We improved the complexity upper bound for repeated reachability from  $\text{NEXPTIME}$  to  $\text{PSPACE}$
- We introduced universal reachability, and showed that it is  $\text{coNEXPTIME}$ -complete
- Verification of regular  $\mathcal{C}$ -expanding properties is also  $\text{NEXPTIME}$ -complete

Thank you !